

CSC 4255 – IoT System Design and Implementation

IoT devices & IoT communication protocols
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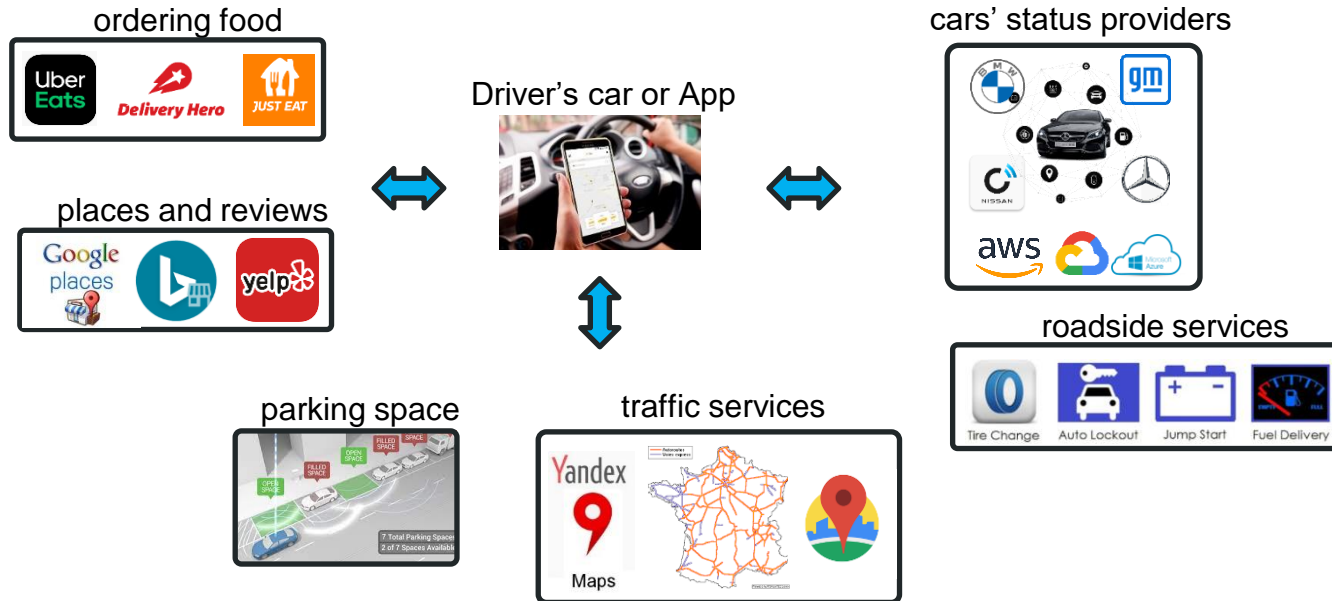
Winter 2024 - 2025

Outline





- The “Things” in the IoT
- Sensors & Actuators
- Smart Objects
- Conclusion

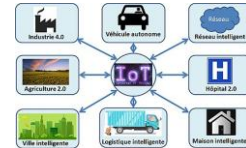
Connected Roadways thanks to the IoT

- IoT allows self-driving vehicles to “better” interact with the transportation system
- Also called IoV (Internet of Vehicles)




The “Things” in connected roadways

- **Sensors** of all types: temperature, location [GPS], pressure, velocity 
- Embedded technology to **sense** and/or interact with their environment 
- **Actuators** to control cars and improve safety 
- **Smart objects** process “raw data” for meaningful and relevant data 
- **Applications** to improve driver experience and simplify vehicle maintenance
- **Communication nodes** for the above to interact with each other



Sensors (1)

- A sensor “It senses”:
 - It measures some physical quantity and converts that measurement reading into a digital representation
 - Digital representation → transformation into meaningful data
 - Human senses:
 - Five senses to learn about their surroundings (not operating in silos)
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TASTE HEARING SIGHT SMELL TOUCH
- Brain: ultimate decision maker
- Sensors: superhuman sensor capabilities
 - extremely wide spectrum of rich and diverse measurement data

Sensors (2)

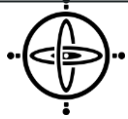
➤ Categories of sensors:

- *Active* emit energy for measuring; *Passive* detect emissions
- *Invasive* part of the environment they are measuring; *Non-invasive* external to the environment
- *Contact* if require physical contact; or *No-contact*
- *Absolute* if they measure on an absolute scale; *Relative* if based on variable reference value
- *Area of application*
- *How sensors measure*, e.g., thermoelectric, electrochemical, piezoresistive, optic, electric, fluid mechanic, photoelastic
- *What sensors measure*: apps or physical variables they measure

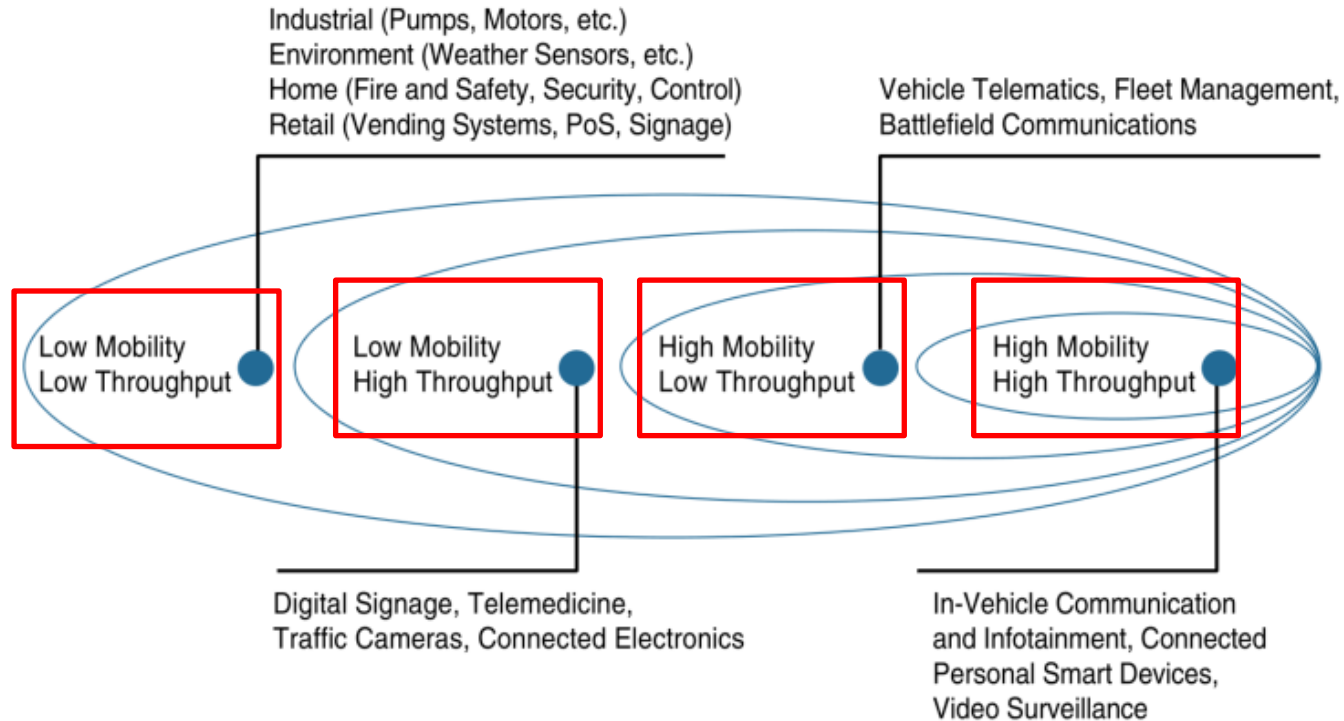
Sensors (3)

➤ Classify based on what physical phenomenon a sensor is measuring

- *Position* (Potentiometer, inclinometer, **proximity sensor**)
- *Occupancy and motion* (Electric eye, **radar**)
- *Velocity and acceleration* (**Accelerometer**, gyroscope)
- *Force* (Force gauge, viscometer, **tactile (touch) sensor**)
- *Pressure* (Barometer, Bourdon gauge, piezometer)
- *Flow* (Anemometer, **mass flow sensor**, water meter)
- *Acoustic* (Microphone, geophone, **hydrophone**)
- *Humidity* (Hygrometer, humistor, **soil moisture sensor**)
- *Light* (**Infrared sensor**, photodetector, flame detector)
- *Radiation* (Geiger-Müller counter, scintillator, **neutron detector**)
- *Temperature* (Thermometer, calorimeter, temperature gauge)
- *Chemical* (Breathalyzer, olfactometer, smoke detector)
- *Biosensors* (Blood glucose biosensor, pulse oximetry, electrocardiograph)

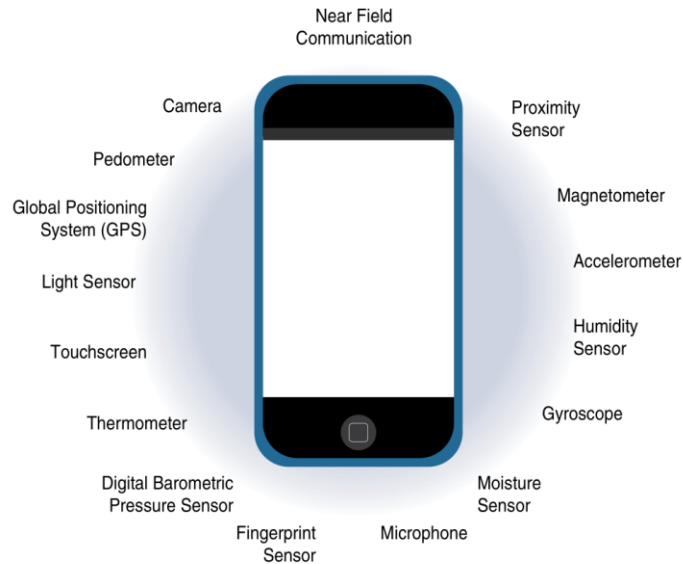


Sensors (4)



What made smartphones smart?

- Touchscreens, accelerometers, gyroscopes, GPS, cameras, etc ...



Sensor examples: Distance/range



1. **IR sensors:** Contain an infrared emitter, and an infrared detector

- Works by emitting a certain amount of infrared light, and seeing how much it gets back
- Why infrared ?
 - There are not so many other infrared sources in everyday life that would interfere with this sensor
 - If visible light were used, light bulbs, computer screens, cellphone screens, etc., would all interfere with the depth reading

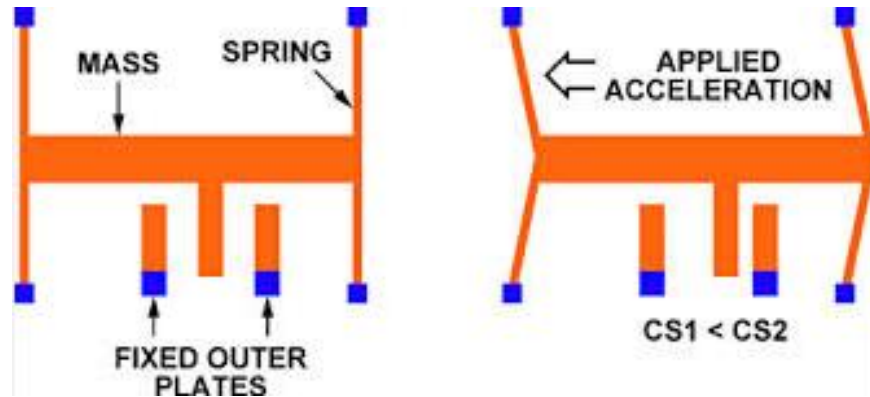
2. **Ultrasound sensors:** contain a high frequency speaker, and a microphone

- Works just like a sonar, emitting a sound, and listening for the echo to determine range
- Very high frequency sound, it is practically beyond what humans can hear.
 - Pros: More accurate than IR sensors at slightly longer distance (typically up to several feet)
 - Cons: Almost twice the price



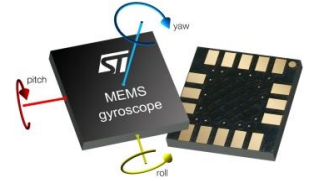
Sensor examples: Accelerometers

- Measure change in velocity in axial dimensions (typically 3 axes)
- How does it work?
 - ❑ The “proof mass” shown is allowed to move in a plane.
 - ❑ The attached fingers form a capacitor with the two plates around it.
 - ❑ The rate of change of the capacities measured and translated into an acceleration



Sensor examples: Gyroscopes

- Measures orientation
- How does it work?
 - If an object is moving along one axis, and it is rotated about another, it will feel a Coriolis force in the third axial direction
 - A gyroscope will have a mass oscillating back and forth along the first axis, and plates on either side of the mass in the third direction (direction of the Coriolis force)
 - When a rotation is detected around the second direction, the capacitance changes



Sensing Properties

Input Range

- the operating range to which the sensor is sensing **{-20°C to 40°C}**

Output Range

- range of the output value **[0, +5V], [0...255]**

Sensitivity

- How much of a change in input signal is needed for a change in the output signal?

Latency:

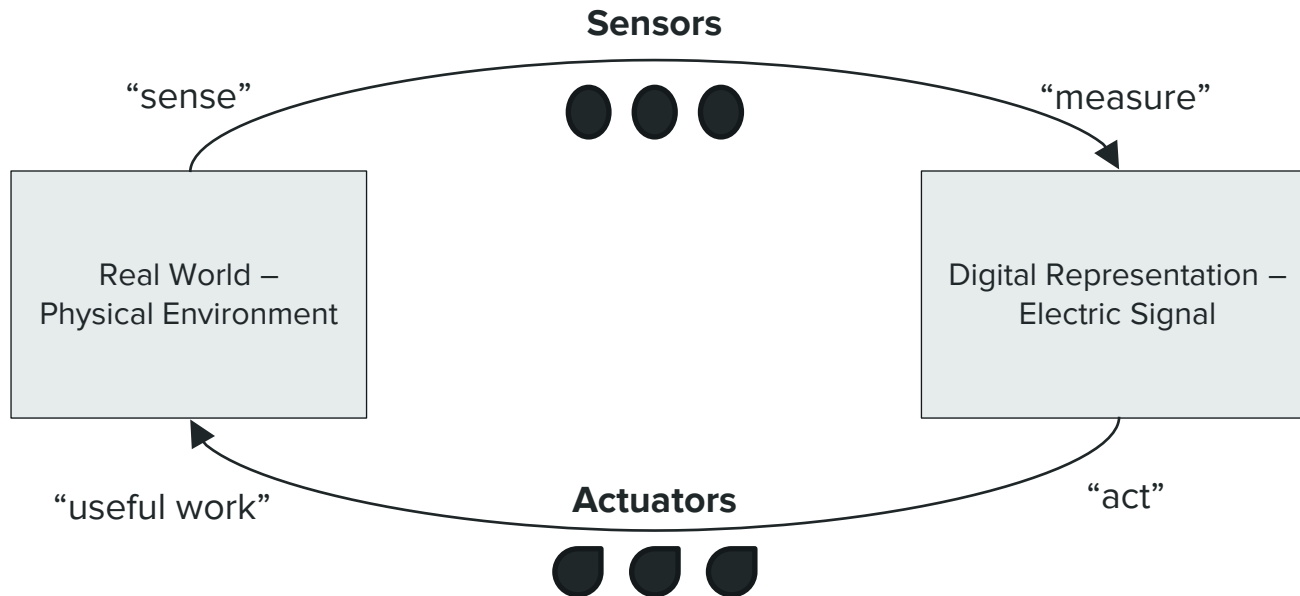
- Speed with which sensor detects/reacts to change

Stability/Drift:

- insensitivity to factors other than measured physical quantity

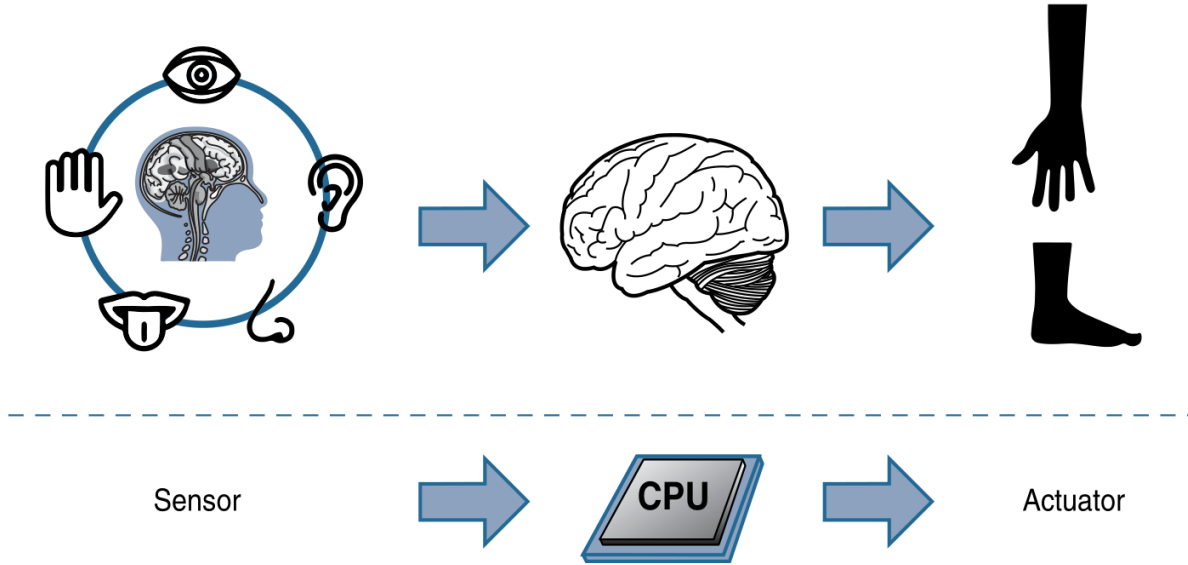
Actuators (1)

- Natural complements to sensors



Actuators (2)

- Comparison of Sensor and Actuator Functionality with Humans



Actuators (3) – types

- Actuators also vary greatly in function, size, design
 - *Type of motion* (linear, rotary, one/two/three-axes)
 - *Power* (high power, low power, micro power)
 - *Binary or continuous* (number of stable-state outputs)
 - *Area of application*
 - *Type of energy*

Actuators (4) – by energy types

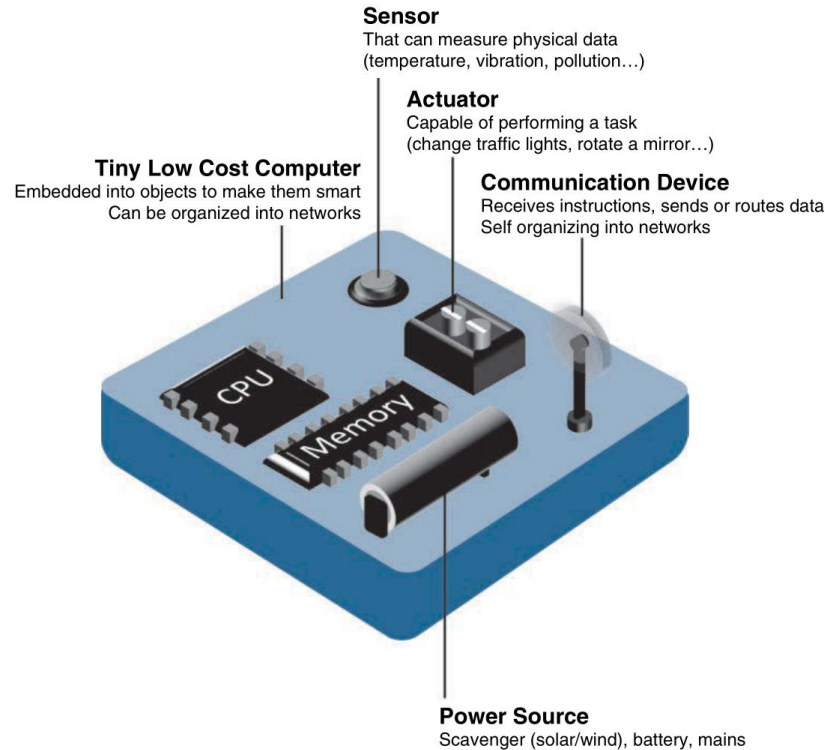
- *Mechanical actuators* (lever, screw jack, hand crank)
- *Electrical actuators* (thyristor, biopolar transistor, diode)
- *Electromechanical actuators* (AC motor, DC motor, step motor)
- *Electromagnetic actuators* (electromagnet, linear solenoid)
- *Hydraulic and pneumatic actuators* (hydraulic cylinder, pneumatic cylinder, piston, pressure control valves, air motors)
- *Smart material actuators* (shape memory alloy (SMA), ion exchange fluid, magnetostrictive material, bimetallic strip, piezoelectric bimorph)
- *Micro- and nanoactuators* (electrostatic motor, microvalve, comb drive)

Smart Objects (1)

- Building blocks of IoT
- A smart object is a device that has, at a minimum, the following four defining characteristics
 - Processing unit
 - Sensor(s) and/or actuator(s)
 - Communication device
 - Power source

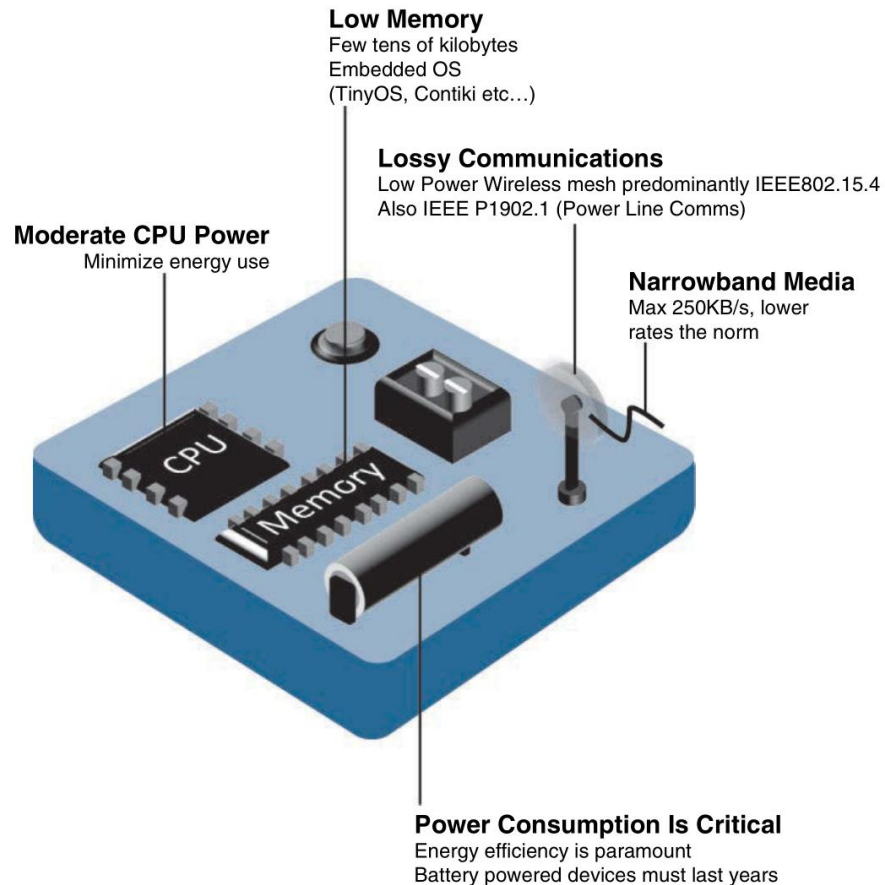
Smart Objects (2)

- Able to learn from and interact with the environment



Wireless communication between smart objects

➤ Constraint nodes



Exercise: Identifying Sensors, Actuators, and Smart Obj.

- **Objective:** Apply your knowledge of IoT components to real-world examples.

Instructions:

1. Form **small groups (2–3 students)**.
2. For each of the following scenarios:
 - I. Identify at least **one sensor** involved.
 - II. Identify at least **one actuator** that could be part of the system.
 - III. Determine if a **smart object** is described, and explain why.

➤ Scenarios:

1. *Smart Home Thermostat:* Automatically adjusts the temperature based on the weather and user preferences.
2. *Smart Irrigation System:* Waters plants based on soil moisture levels and weather forecasts.
3. *Fitness Tracker:* Tracks heart rate and steps, sending the data to a mobile app.
4. *Parking Garage System:* Uses cameras to detect available spaces and displays them on a digital board.

Time: 10 minutes

Tip: Focus on the *input (sensor)*, *output (actuator)*, and *intelligence (smart object)* of the system.

Conclusion

- “Things” in the IoT
- Sensors have properties important for applications and system planning/design
- Actuators are used to optimize the application
- Smart objects are platforms with sensing, actuating, processing and communicating capabilities

Thank you



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