Abstracting Interactions with IoT Devices Towards a Semantic Vision of Smart Spaces



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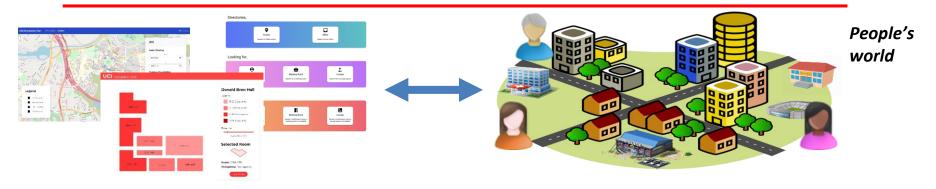
IoT Application Development

-Constrained to specific devices/protocols -Difficult to port to other IoT spaces -Developer needs to understand the devices in the IoT space which makes development challenging





IoT Application Development



App request:

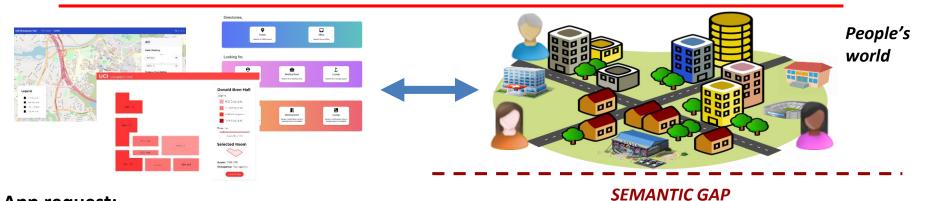
"Decrease temperature of rooms with occupancy above 50% of their capacity."

User/Space policy:

"Do not capture the location of John and Mary when they are in their offices."



Challenge: Semantic Gap



App request:

"Decrease temperature of rooms with occupancy above 50% of their capacity."

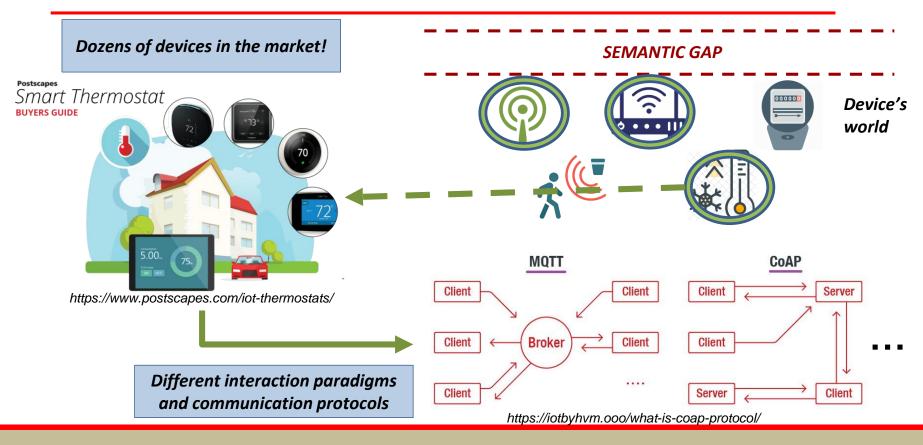
User/Space policy:

"Do not capture the location of John and Mary when they are in their offices."

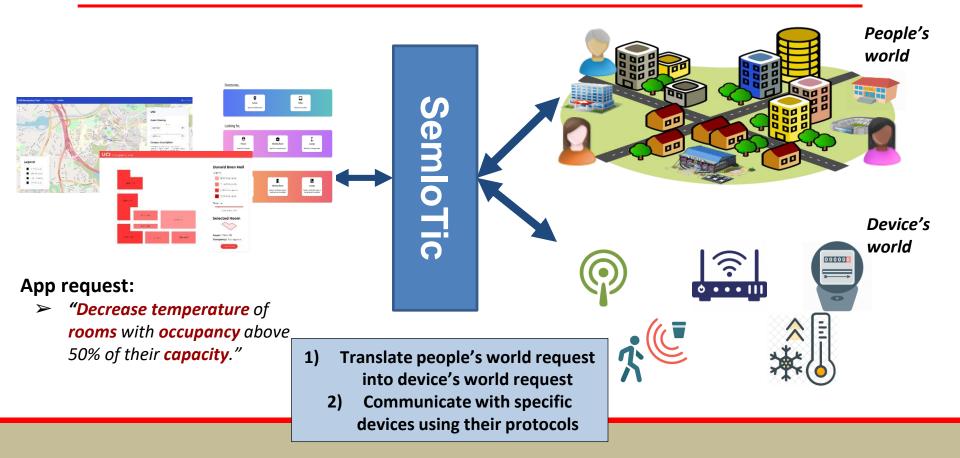


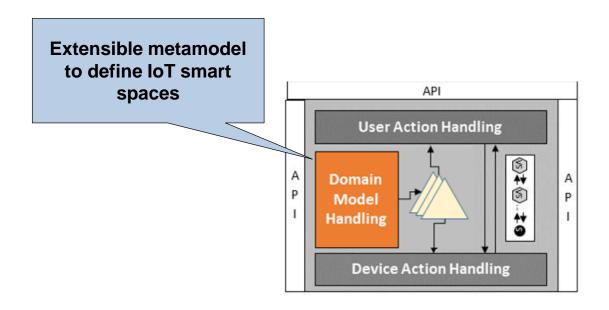
Which sensors/actuators can we use to answer such request/policy?

Challenge: IoT Heterogeinity

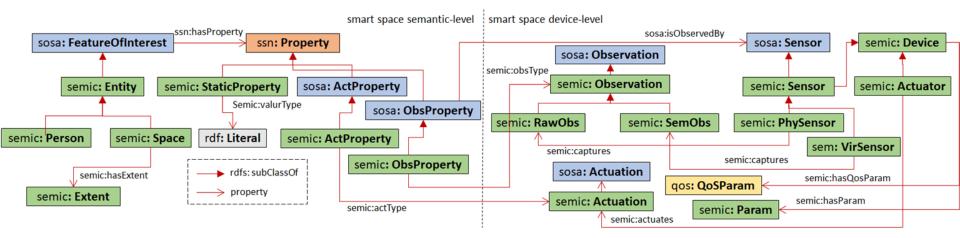


SemIoTic: End-to-End IoT Framework

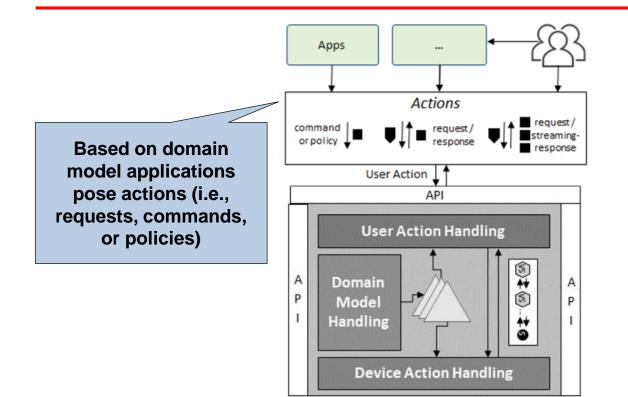




Modeling IoT Spaces



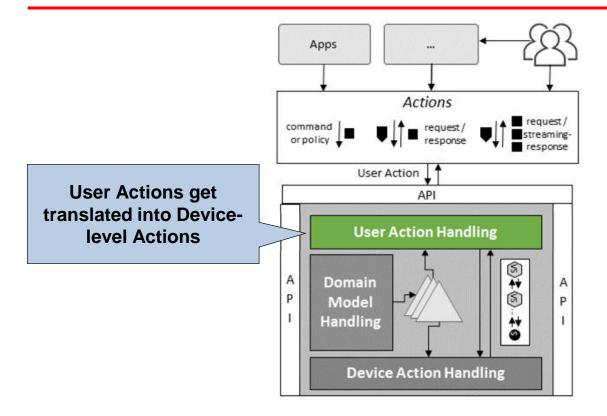
- Defining IoT spaces using an **ontology** provides **flexibility** and **extensibility**.
 - In addition, **semantic reasoning** to infer non-explicitly defined information (e.g., *if occupancy is a property of rooms, it should be also of meeting room 2065*).
- Created **OWL meta ontology (semic)** extending the popular sensor ontology (**SSN/SOSA**)
 - Focus on representing the connection between *"people's world"* and *"device's world"*.
 - Properties of people/spaces (e.g., location, occupancy, temperature) connected to sensors/actuators based on expected value types and produced value types.



Defining User Actions

- User Actions (UA), expressed at the semantic-level:
 - Requests for data (UR)
 - Commands (UC)
 - Policies (UP)
- Language for definition of general UAs with following elements:
 - Entities of interest (E) \rightarrow Set of entities e_i , either entity classes $(e_i, rdfs:subClassOf, semic:Entity)$ or entity instances $(e_i, rdf:type, semic:Entity)$
 - **Properties of interest (P)** \rightarrow Set of properties p_i (p_i , rdf:type,semic:Property).
 - Conditions (C) → expression containing properties that has to be satisfied to perform the actions on the entities
 - (For UP) Interaction to control (i.e., capture, store, share) and preferred action (i.e., accept or deny).

UR	"retrieve the current location of John and Mary"	<pre>(<mary, john="">, Location)</mary,></pre>
UC	<i>"decrease temp. of rooms with occ. above 50% of their capacity"</i>	(Room, ControlTemp, Occupancy>0.5xCapacity)
UP	<i>"do not capture Mary's and John's location in private spaces when the occupancy is less than 2 people"</i>	<pre>{<mary, john="">, Location subClassOf PrivateSpace, Location.Occupancy<2, capture, deny}</mary,></pre>



Translating User Actions

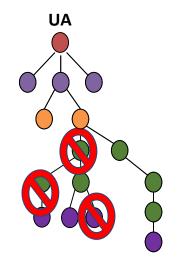
- Goal:
 - Create a plan involving IoT devices to process a UA.
- Ontology-based translation algorithm that can process policies as well as requests/commands defined at a higher-level.

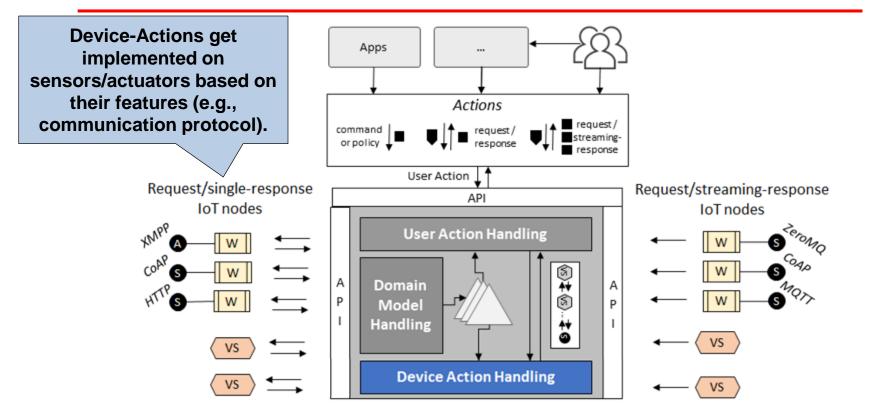
Plans can be infeasible if sensors are not available (e.g., due to privacy policies)

Selection based on metrics (e.g., economical cost, latency, reliability)

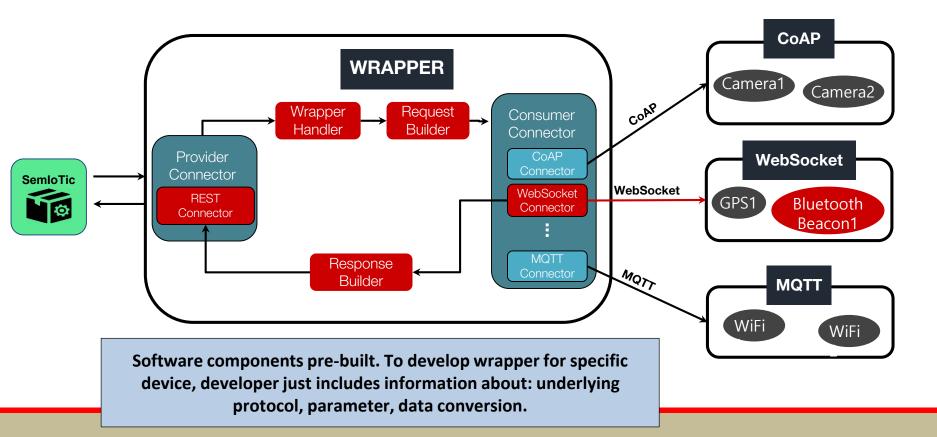
User Action Translation

- 1) Flattening
- 2) Plan Generation
- 3) Realizability Checking
- 4) Feasibility Checking
- 5) Plan Selection

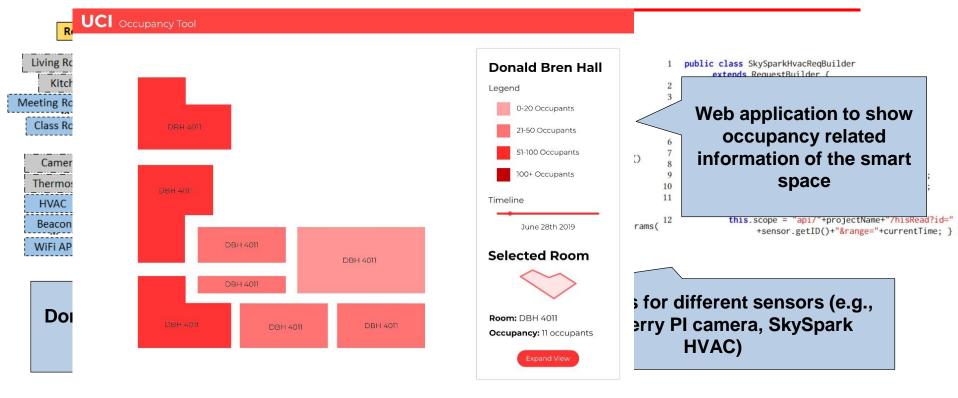




Device Action Handling



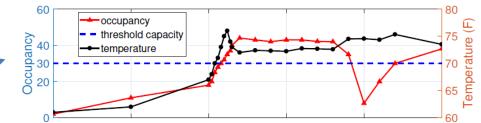
Using SemIoTic



Using SemIoTic



Same application and same request but different underlying sensors used by SemIoTic



SemioTic (Smart Building)

SemloTic

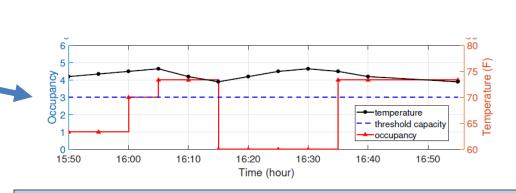
(Smart Home)

currentTime: }

omions

CapProp RegTempProp PresProp





Reduction of development effort (in terms of LoC) by 55% to 97%

